



RT70E

越野轮胎起重机 Rough Terrain Crane



70t×2.5m



43.2m



9.5m+8m





产品特点 Features



主臂 Main Boom

11.32m-43.2m五节主臂，双缸绳排伸缩系统。一级缸带动二节臂伸缩，二级缸带动三、四、五节臂同步伸缩，吊臂同步、顺序伸缩。

11.32 m – 43.2 m, five-section. Double-cylinder plus rope principle is used for telescoping the boom. The 1st-stage cylinder pulls the 2nd boom section, the 2nd-stage cylinder drives 3rd, 4th and 5th. The boom is extended and retracted by the way of sequence plus synchronization.



副臂 Jib

两节侧置副臂，第一节副臂采用桁架臂，臂长9.5m；第二节副臂采用箱型结构，臂长8m；副臂安装角分别为0°、20°、40°。

Two sections(Optional configuration). the first jib section is lattice, 9.5m long, the second jib section is box structure, 8m long.
three offset angles of 0° , 20° and 40° .
Stows alongside base boom section.



回转 Swing

回转机构采用液压马达驱动，内置行星齿轮减速和常闭式制动器。单排四点接触球式回转支承，可360° 范围内连续回转，滚柱轨道密封，可防水防尘。

Swing system is driven by a hydraulic motor, with built-in planetary gear reducer and normally closed brake fitted. Single-row four-point ball contact slewing ring, it can slew 360° continuously, roller raceway seal is water proof and dust proof.



卷扬 Winch

液压马达驱动，内置行星齿轮减速机和常闭式制动器，配置抗缠绕钢丝绳，主、副起升机构单独运转。

Driven by a hydraulic motor, with build-in planetary gear reducer, normally closed brake and anti-winding wire rope equipped. Main and auxiliary hoist systems can be operated separately.



变幅系统 Elevating system

一根装平衡阀的双作用液压油缸，吊臂变幅角度：-2° ~ 80° 。

One double-acting oil cylinder with a balance valve equipped.
Elevating angle: -2° ~ 80° .



配重 Counterweight

自拆装组合式平衡重，0t、5.5t和9t三种配重工况。

Self-erecting combined counterweight.
Three working conditions separately with 0t, 5.5t and 9 t of counterweight fitted.



产品特点 Features



司机室 Cab

驾驶室、操纵室一体化设计，外观简洁、动感。全天候大圆弧玻璃，视角开阔；人机工程设计的内部空间，宽敞舒适。

Cab of integrated design is simple and artistic. It is all-weather and streamlined and has a wide field of view, as well as spacious and comfortable due to ergonomic inner design.



吊钩 Hook

标配：

35t钩，3组滑轮

Standard configuration: 35t hook, 3 Sheave block.



液压系统 Hydraulic System

起重作业部分采用电控先导操纵系统，先导阀采用电比例控制阀，先导阀手柄移动的角度、主操纵阀的阀芯开口位移与输入电流成正比，主操纵阀的阀芯位移与马达、油缸等执行元件的运动速度也成正比，整机具有良好的微动性。

液压油箱容量：900L

Hydraulic system for lifting operation: in the electro-proportional control system, the pilot valve is an imported electro-proportional control valve. The moving angle of the pilot valve handle is directly proportional to the input current, and the valve spindle displacement of main control valve is directly proportional to the input current of the pilot valve, as well as the moving speed of actuator such as motor and oil cylinder. Thus fine inching control is available in the whole machine.

Oil tank capacity: about: 900L.



电气系统 Electric System

电气系统采用24V DC，2个蓄电池，负极搭铁。照明系统配置有前大灯、雾灯、倒车灯及转向灯等。

24V DC from 2 batteries, with negative ground.
Illumination includes head lamp, fog lamp, reversing lamp and steering lamp, etc.



发动机 Engine

美国康明斯发动机，直列六缸、水冷却、增压中冷、压燃式柴油发动机

功率：194kW/2200 r/min

排放标准：北美非道路Tier3/欧洲非道路Stage IIIA.

Developed by Ammerica Cummins.
six-cylinder, in line, water cooled, supercharging intercooler, compression ignition diesel engine.
Power: 194kW/2200r/min.
off-road,U.S.EPA Tier 3/EU Stage IIIA.



变速箱 Transmission

德国ZF专为越野轮胎起重机开发的变速箱，具有6个前进档和3个倒退档，手自一体，两种操作模式。

Developed by German ZF for RT Crane.
6-Speeds forward and 3-Speeds reverse.
Two operation modes :automatic, manual.



车桥及悬架 Axle and Suspension

德国kessler专为越野轮胎起重机开发的车桥。前后桥均为转向驱动桥，承载能力大，可靠性高，维护方便。前桥与车架之间刚性连接；后桥通过悬挂油缸与车架连接，当转台旋转角度超过 $\pm 3^\circ$ 时，可通过液压系统将悬挂油缸切换至刚性状态。

Developed by German Kessler for RT Crane.
Both front axle and rear axle are driven, they have heavy load-bearing capacity and high reliability, and are easy to maintain.
Front axle is connected with frame rigidly;
Rear axle is connected with frame by swing suspension, which can be locked to rigid state by hydraulic system when the turntable is slewed more than $\pm 3^\circ$.



转向 Steer

全液压电比例多模式转向系统，具有前桥独立转向、小转弯转向、蟹行转向和后桥独立转向功能。
最小转弯半径：6.1m。

Full hydraulic electro-proportional multi-mode steering: front axle independent steering, small turning radius steering, crab walk steering and rear axle independent steering are available.
Min. turning radius: 6.1m.



制动 Brake

行车制动：采用双回路全液压盘式制动，作用于所有车轮；
驻车制动：弹簧加载，液压解除的独立盘式制动器，作用于前桥。

Service brake: double-circuit full-hydraulic disc brake, acting on all wheels.
Parking brake: spring-loaded brake, hydraulic-released independent disc brake, acting on front axles.



轮胎 Tire

29.5R25的子午线轮胎，承载能力大，专用的越野花纹轮胎，适合越野轮胎起重机的各种使用工况要求。

29.5R25 radial ply tire, heavy load-bearing capacity, with specialized off-road tire patterns, compliant with the working condition requirements of rough terrain crane.



支腿 Outrigger System

四组独立的水平支腿、垂直支腿，可在司机室内独立控制。
支腿跨距：
纵向：7.3m；
横向（全伸/半伸）：7.2m/5.6m。

Four independent horizontal beams and vertical jacks with integral holding valves, each independently controlled from cab.
Outrigger span:
Longitudinal: 7.3m;
Lateral(fully/half extended): 7.2m/5.6m.



力矩限制器 Load Moment Limiter

赫斯曼力矩限制器系统，采用先进的微处理器技术，其功耗小、功能强、灵敏度高、操作简便。大屏幕的液晶显示器，以中文和图形方式显示力矩百分比、实际起重量、额定起重量、幅度、吊臂长度、角度、最大起升高度、工况代码、倍率、限制角度、信息代码等起重作业参数。具有完整的预先报警、超载停止作业功能，同时还具有超载记忆功能（黑匣子）和故障自诊断功能。

Hirschman Load moment limiter system with advanced micro-processing technology employed, has features of less power consumption, powerful function and high sensitivity, and is easy to operate. LCD with large screen will show the lifting operation data, such as moment percentage, actual lifting capacity, rated lifting capacity, working radius, boom length, boom angle, max. lifting height, working condition code, parts of line, limited angle, information code, etc. by means of Chinese and graphical symbol. It has complete forewarning and overloading cutout function, as well as overloading memory (black box) and fault self-diagnosis function.



选装配置 Optional configuration

空调及加热器；
70t吊钩，7组滑轮；
5t吊钩；差速锁；
17.5m副臂。

Air conditioner and heater.
70t hook, 7 Sheave block;
5t hook. Differential lock.
Jib, 17.5m long.

技术规格（遵从技术改进）
Specifications(Subject to technology improvement)



行驶状态主要技术参数表 Main technical data in travel configuration

类别 Category	项目 Item		参数 Parameter	允差范围 Allowance	
尺寸参数 Dimension	整机全长 Overall length(include single top)		mm	13401	± 1%
	整机全宽 Overall width		mm	3180	-1%~0
	整机全高 Overall height		mm	3750	-1%~0
	轴距 Wheel base		mm	4000	± 1%
	轮距（前/后） Track (front/rear)		mm	2400	± 1%
	前悬/后悬 Front/rear overhang		mm	1925/2190	± 1%
	前伸/后伸 Front/rear extension		mm	5020/0	± 1%
重量参数 Weight	行驶状态总质量（包括选配部件） Total mass（including optional parts）		kg	49000	± 3%
	轴荷 Axle load	一轴 Front Axle	kg	25000	± 3%
		二轴 Rear Axle	kg	24000	± 3%
行驶参数 Travel	最高行驶速度 Max. travel speed		km/h	25	≥
	最小转弯半径 Min. turning radius		m	6.1(四轮), 10.5（两轮） 6.1(4 wheels),10.5 (2 wheels)	± 3%
	最小离地间隙 Min. ground clearance		mm	467	± 1%
	接近角 Approach angle		°	20	± 1%
	离去角 Departure angle		°	17.5	± 1%
	制动距离(制动初速度为24km/h) Braking distance (24 km/h)		mm	9	≤
	最大爬坡能力 Max. grade-ability		%	65	≥
动力参数 Power	发动机型号 Engine model			QSB6.7	/
	发动机额定功率 Rated engine power		kW	194	/
	发动机额定转速 Engine rated rotation speed		r/min	2200	/
	发动机排放标准 Engine emission standard		—	off-road, U.S.EPA Tier 3/ EU Stage IIIA.	/
	驱动型式 Driving type		—	4×2, 4×4	/
	轮胎规格 Tire specifications		—	26.5R25	/
	轮胎数量 Number of tires		—	4	/



起重作业状态主要技术参数表 Main technical data for lifting operation

类别 Category	项目 Item			参数 Parameter	允差范围 Allowance	
主要性能参数 Main performance	最大额定总起重量 Max. rated lifting capacity			t	70	± 5%
	最小额定幅度 Min. rated working radius			m	2.5	± 1%
	转台尾部回转半径（平衡重） Slewing radius at turntable tail (at counterweight)			mm	4100	± 1%
	最大起重力矩 Max. load moment	基本臂 Base boom		kN · m	2033	± 5%
		最长主臂 Fully-extended boom		kN · m	1223	± 5%
	支腿跨距 Outrigger span	纵向 Longitudinal		m	7.3	± 1%
		横向（全伸/半伸） Lateral(fully/half extended)		m	7.2/5.6	± 1%
	起升高度 Lifting height	基本臂Base boom		m	11.3	± 1%
		最长主臂 Fully-extended boom		m	43.3	± 1%
		最长主臂+副臂 Fully-extended boom + Jib		m	58.1	± 1%
	起重臂长度 Boom length	基本臂 Base boom		m	11.32	± 1%
		最长主臂 Fully-extended boom		m	43.2	± 1%
		最长主臂+副臂 Fully-extended boom + Jib		m	60.7	± 1%
	副臂安装角 Jib offset angle			°	0° , 20° , 40°	± 1%
作业速度 Working speed	主臂起臂时间 Time for boom raising			s	80	≤
	主臂全伸时间 Time for boom extending fully			s	110	≤
	最大回转速度 Max. slewing speed			r/min	2.0	≥
	支腿收放时间 Outrigger extending/ retracting time	水平支腿 Outrigger beam	同时放 Simultaneously extending	s	40	≤
			同时收 Simultaneously retracting	s	30	≤
		垂直支腿 Outrigger jack	同时放 Simultaneously extending	s	55	≤
			同时收 Simultaneously retracting	s	40	≤
	起升速度(空载四层) Hoisting speed (at 4th layer, no load)	主起升机构 Main winch		m/min	130	≥
		副起升机构 Auxiliary winch		m/min	130	≥

起重性能表Load charts



说明 Notes

警告：本起重性能表仅供参考，下面的注释仅仅是简单的说明，不能直接用于操作起重机的依据。在操作起重机前，必须熟读起重机的起重性能表、操作手册和其它说明。

Warning: THIS CHART IS ONLY A GUIDE. The Notes below are for illustration only and should not be relied upon to operate the crane. The individual crane's load chart, operating instructions and other instruction plates must be read and understood prior to operating the crane.

1.表中给出的起重量不包括吊钩、索具以及其他辅助装置的重量，起重量等于载荷物重量与吊装索具重量之和。当使用的钢丝绳大于最小需求倍率时，额外的钢丝绳重量也要考虑到起重载荷中。

1. Capacities given do not include the weight of hookblocks, slings, auxiliary lifting equipment and load handling devices. Their weights must be added to the load to be lifted. When more than minimum required reeving is used, the additional rope weight shall be considered part of the load.

2.表中的起重量值，都针对在坚固、平整的地面上操作的起重机。为获得更大的支承面，可在轮胎或支脚盘下方铺设垫板。

2. All capacities are for crane on firm, level surface. It may be necessary to have structural supports under the outrigger flats or tyres to spread the load to a larger bearing surface.

3.当主臂臂长或幅度在表中所列值的范围之间时，应使用下一个较大半径或较长主臂长度所列出的最小起重量。

3. When either boom length or radius or both are between values listed, the smallest load shown at either the next larger radius or boom length shall be used.

4.对于使用支腿工况，在起臂或吊重作业前，应将支腿完全伸出且使轮胎离地。

4. For outrigger operation, ALL outriggers shall be fully extended with tyres raised free of ground before raising the boom or lifting loads.

5.对于使用轮胎工况，轮胎气压应达到规定值。

5. Tyres shall be inflated to the recommended pressure before lifting on rubber.

6.对于副臂处于作业状态而使用主臂吊重时，主臂的额定起重量至少要减去1500kg。

6. For jib operation, The rated capacities of the main boom should be reduce at least 1500kg when lifting loads with main boom.





起重性能表Load charts

起重性能表 Load charts



11.32–43.2m



7.2m



360°



9t

R/L	11.32	15.30	19.28	25.67	32.86	40.04	43.20
2.5	70.0*						
3.0	65.0						
3.5	54.7	42.0					
4.0	50.0	42.0	35.0				
5.0	41.5	40.8	34.0	26.0			
6.0	33.5	32.6	31.5	25.4	18.0		
7.0	28.0	27.0	26.5	23.9	17.5	12.0	
8.0	23.5	22.8	22.5	23.0	17.2	12.0	9.0
9.0		19.0	18.5	19.0	17.0	11.5	9.0
10.0		16.7	16.4	17.0	16.5	11.2	8.7
12.0		11.2	11.0	12.5	13.2	10.1	8.5
14.0			7.6	9.1	10.0	9.7	8.1
16.0				6.7	7.6	8.2	7.8
18.0				5.0	5.9	6.4	6.6
20.0				3.7	4.5	5.1	5.3
22.0				2.7	3.5	4.0	4.2
24.0					2.7	3.2	3.4
26.0					2.0	2.5	2.7
28.0					1.4	1.9	2.1
30.0						1.4	1.6
32.0						1.0	1.2
34.0						0.6	0.8
倍率 Parts of line	14	9	7	5	4	3	3
最大仰角 Max. boom angle (°)	65	70	74	76	78	79	79
最小仰角 Min. boom angle (°)	26	22	34	20	25	27	36
2节臂 2nd section	0.0%	50.0%	100.0%	100.0%	100.0%	100.0%	100.0%
3节臂 3rd section	0.0%	0.0%	0.0%	26.7%	56.7%	86.7%	100.0%
4节臂 4nd section	0.0%	0.0%	0.0%	26.7%	56.7%	86.7%	100.0%
5节臂 4nd section	0.0%	0.0%	0.0%	26.7%	56.7%	86.7%	100.0%

注：“*”为理论计算值，该工况需要特殊装置。

Notes: The value of “*” is theoretical value, A special device is required for operation under the working condition.

起重性能表Load charts



起重性能表 Load charts



11.32–35.5m



7.2m



360°



5.5t

R/L	11.32	15.30	19.28	25.67	32.86	40.04	43.20
2.5	70.0*						
3.0	65.0						
3.5	54.7	42.0					
4.0	50.0	42.0	35.0				
5.0	41.5	40.8	34.0	26.0			
6.0	33.5	32.6	31.5	25.4	18.0		
7.0	28.0	27.0	26.5	23.9	17.5	12.0	
8.0	23.2	22.7	22.4	23.0	17.2	12.0	9.0
9.0		17.4	17.1	18.9	17.0	11.5	9.0
10.0		13.7	13.4	15.1	16.2	11.2	8.7
12.0		8.9	8.7	10.2	11.2	10.1	8.5
14.0			5.8	7.2	8.1	7.6	7.8
16.0				5.1	6.0	5.8	6
18.0				3.6	4.5	4.5	4.7
20.0				2.5	3.3	3.5	3.7
22.0				1.6	2.4	2.8	2.9
24.0					1.7	2.1	2.3
26.0					1.1	1.6	1.7
28.0					0.6	1.2	1.3
30.0						0.8	0.9
32.0							
34.0							
倍率 Parts of line	14	9	7	5	4	3	3
最大仰角 Max. boom angle (°)	65	70	74	76	78	79	79
最小仰角 Min. boom angle (°)	26	22	34	20	25	39	45
2节臂 2nd section	0.0%	50.0%	100.0%	100.0%	100.0%	100.0%	100.0%
3节臂 3rd section	0.0%	0.0%	0.0%	26.7%	56.7%	86.7%	100.0%
4节臂 4nd section	0.0%	0.0%	0.0%	26.7%	56.7%	86.7%	100.0%
5节臂 4nd section	0.0%	0.0%	0.0%	26.7%	56.7%	86.7%	100.0%

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起重性能表Load charts

起重性能表 Load charts



11.32–43.2m



7.2m



360°



0t

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3.0	65.0						
3.5	54.7	42.0					
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6.0	27.6	27.0	26.6	25.4	18.0		
7.0	19.6	19.0	18.7	20.7	17.5	12.0	
8.0	14.6	14.1	13.9	15.6	16.8	12.0	9.0
9.0		10.8	10.6	12.2	13.3	11.5	9.0
10.0		8.4	8.2	9.7	10.8	11.2	8.7
12.0		5.2	5.0	6.4	7.3	7.9	8.1
14.0			2.9	4.3	5.1	5.7	5.9
16.0				2.8	3.6	4.1	4.3
18.0				1.7	2.5	3.0	3.2
20.0				0.8	1.6	2.1	2.3
22.0					0.9	1.4	1.6
24.0						0.9	1.0
26.0							
28.0							
30.0							
32.0							
34.0							
倍率 Parts of line	14	9	7	5	4	3	3
最大仰角 Max. boom angle (°)	65	70	74	76	78	79	79
最小仰角 Min. boom angle (°)	26	22	34	20	25	27	36
2节臂 2nd section	0.0%	50.0%	100.0%	100.0%	100.0%	100.0%	100.0%
3节臂 3rd section	0.0%	0.0%	0.0%	26.7%	56.7%	86.7%	100.0%
4节臂 4nd section	0.0%	0.0%	0.0%	26.7%	56.7%	86.7%	100.0%
5节臂 4nd section	0.0%	0.0%	0.0%	26.7%	56.7%	86.7%	100.0%

注：“*”为理论计算值，该工况需要特殊装置。

Notes: The value of “*” is theoretical value, A special device is required for operation under the working condition.

起重性能表 Load charts



起重性能表 Load charts



11.32–43.5m



5.6m



360°



9t

R/L	11.32	15.30	19.28	25.67	32.86	40.04	43.20
2.5	70.0*						
3.0	65.0						
3.5	54.7	42.0					
4.0	50.0	42.0	35.0				
5.0	41.5	40.8	34.0	26.0			
6.0	33.1	32.4	31.5	25.4	18.0		
7.0	23.7	23.2	22.9	23.9	17.5	12.0	
8.0	17.9	17.5	17.2	19.0	17.2	12.0	9.0
9.0		13.6	13.4	15.0	16.1	11.5	9.0
10.0		10.8	10.6	12.2	13.2	11.2	8.7
12.0		7.1	6.9	8.3	9.2	9.8	8.5
14.0			4.5	5.8	6.7	7.3	7.4
16.0				4.1	4.9	5.5	5.6
18.0				2.8	3.6	4.1	4.3
20.0				1.8	2.6	3.1	3.3
22.0				1.0	1.8	2.3	2.5
24.0					1.2	1.7	1.8
26.0					0.7	1.1	1.3
28.0						0.7	0.8
30.0							
32.0							
34.0							
倍率 Parts of line	14	9	7	5	4	3	3
最大仰角 Max. boom angle (°)	65	70	74	76	78	79	79
最小仰角 Min. boom angle (°)	26	22	34	20	33	43	49
2节臂 2nd section	0.0%	50.0%	100.0%	100.0%	100.0%	100.0%	100.0%
3节臂 3rd section	0.0%	0.0%	0.0%	26.7%	56.7%	86.7%	100.0%
4节臂 4nd section	0.0%	0.0%	0.0%	26.7%	56.7%	86.7%	100.0%
5节臂 4nd section	0.0%	0.0%	0.0%	26.7%	56.7%	86.7%	100.0%

注：“*”为理论计算值，该工况需要特殊装置。

Notes: The value of “*” is theoretical value, A special device is required for operation under the working condition.



起重性能表Load charts

起重性能表 Load charts



11.32-43.2m



5.6m



360°



5.5t

R/L	11.32	15.30	19.28	25.67	32.86	40.04	43.20
2.5	70.0*						
3.0	65.0						
3.5	54.7	42.0					
4.0	50.0	42.0	35.0				
5.0	41.5	40.8	34.0	26.0			
6.0	27.6	27.0	26.6	25.4	18.0		
7.0	19.6	19.0	18.7	20.7	17.5	12.0	
8.0	14.6	14.1	13.9	15.6	16.8	12.0	9.0
9.0		10.8	10.6	12.2	13.3	11.5	9.0
10.0		8.4	8.2	9.7	10.8	11.2	8.7
12.0		5.2	5.0	6.4	7.3	7.9	8.1
14.0			2.9	4.3	5.1	5.7	5.9
16.0				2.8	3.6	4.1	4.3
18.0				1.7	2.5	3.0	3.2
20.0				0.8	1.6	2.1	2.3
22.0					0.9	1.4	1.6
24.0						0.9	1.0
26.0							
28.0							
30.0							
32.0							
34.0							
倍率 Parts of line	14	9	7	5	4	3	3
最大仰角 Max. boom angle (°)	65	70	74	76	78	79	79
最小仰角 Min. boom angle (°)	26	22	34	32	45	51	56
2节臂 2nd section	0.0%	50.0%	100.0%	100.0%	100.0%	100.0%	100.0%
3节臂 3rd section	0.0%	0.0%	0.0%	26.7%	56.7%	86.7%	100.0%
4节臂 4nd section	0.0%	0.0%	0.0%	26.7%	56.7%	86.7%	100.0%
5节臂 4nd section	0.0%	0.0%	0.0%	26.7%	56.7%	86.7%	100.0%

注：“*”为理论计算值，该工况需要特殊装置。

Notes: The value of “*” is theoretical value, A special device is required for operation under the working condition.

起重性能表Load charts



起重性能表 Load charts



11.32–43.2m



7.2m



360°



0t

R/L	11.32	15.30	19.28	25.67	32.86	40.04	43.20
2.5	70.0*						
3.0	65.0						
3.5	54.7	42.0					
4.0	50.0	42.0	35.0				
5.0	30.5	29.8	29.3	26.0			
6.0	19.1	18.4	18.1	20.4	18.0		
7.0	13.0	12.5	12.2	14.2	15.5	12.0	
8.0	9.3	8.9	8.6	10.4	11.5	12.0	9.0
9.0		6.4	6.2	7.8	8.9	9.6	9.0
10.0		4.6	4.4	5.9	6.9	7.6	7.8
12.0		2.2	2.0	3.4	4.4	5.0	5.2
14.0			0.5	1.8	2.7	3.3	3.4
16.0				0.7	1.5	2.1	2.3
18.0					0.7	1.2	1.4
20.0							0.7
22.0							
24.0							
26.0							
28.0							
30.0							
32.0							
34.0							
倍率 Parts of line	14	9	7	5	4	3	3
最大仰角 Max. boom angle (°)	65	70	74	76	78	79	79
最小仰角 Min. boom angle (°)	26	22	34	47	55	62	62
2节臂 2nd section	0.0%	50.0%	100.0%	100.0%	100.0%	100.0%	100.0%
3节臂 3rd section	0.0%	0.0%	0.0%	26.7%	56.7%	86.7%	100.0%
4节臂 4nd section	0.0%	0.0%	0.0%	26.7%	56.7%	86.7%	100.0%
5节臂 4nd section	0.0%	0.0%	0.0%	26.7%	56.7%	86.7%	100.0%

注：“*”为理论计算值，该工况需要特殊装置。

Notes: The value of “*” is theoretical value, A special device is required for operation under the working condition.



起重性能表Load charts

起重性能表 Load charts



11.32–32.86m



不行驶 stationary



360°



9t

R/L	11.32	15.30	19.28	25.67	32.86
3.0	25.5				
3.5	21.6	19.9			
4.0	18.6	17.2	16.0		
5.0	12.8	12.3	12.1	12.3	
6.0	8.9	8.5	8.2	9.7	9.8
7.0	6.3	5.9	5.7	7.1	8.0
8.0	4.4	4.1	3.9	5.2	6.1
9.0	14.6	2.8	2.6	3.8	4.7
10.0		1.7	1.5	2.8	3.6
12.0				1.2	2.0
14.0					0.9
倍率 Parts of line	14	9	7	5	4
最大仰角 Max. boom angle (°)	65	70	74	76	78
最小仰角 Min.boom angle (°)	26	22	34	32	45
2节臂 2nd section	0.0%	50.0%	100.0%	100.0%	100.0%
3节臂 3nd section	0.0%	0.0%	0.0%	26.7%	56.7%
4节臂 4nd section	0.0%	0.0%	0.0%	26.7%	56.7%
5节臂 4nd section	0.0%	0.0%	0.0%	26.7%	56.7%

起重性能表Load charts



起重性能表 Load charts



11.32–32.86m



不行驶 stationary



360°



5.5t

R/L	11.32	15.30	19.28	25.67	32.86
3.0	22.4				
3.5	18.9	18.4			
4.0	15.2	14.7	14.4		
5.0	9.6	9.1	8.9	10.5	
6.0	6.3	5.9	5.7	7.2	8.2
7.0	4.2	3.8	3.6	5.0	5.9
8.0	2.7	2.3	2.1	3.4	4.3
9.0		1.2	1.0	2.3	3.1
10.0				1.4	2.2
12.0					0.9
14.0					
倍率 Parts of line	5	4	3	3	3
最大仰角 Max. boom angle (°)	65	70	74	76	78
最小仰角 Min. boom angle (°)	26	22	34	32	45
2节臂 2nd section	0.0%	50.0%	100.0%	100.0%	100.0%
3节臂 3rd section	0.0%	0.0%	0.0%	26.7%	56.7%
4节臂 4nd section	0.0%	0.0%	0.0%	26.7%	56.7%
5节臂 4nd section	0.0%	0.0%	0.0%	26.7%	56.7%



起重性能表Load charts

起重性能表 Load charts



11.32–32.86m



不行驶 stationary



360°



0t

R/L	11.32	15.30	19.28	25.67	32.86
3.0	16.4				
3.5	11.5	10.9			
4.0	8.4	7.8	7.5		
5.0	4.6	4.1	3.9	5.3	
6.0	2.3	1.9	1.7	3.2	4.2
7.0	0.9	0.5		1.7	2.6
8.0				0.6	1.5
9.0					0.7
10.0					
12.0					
14.0					
16.0					
倍率 Parts of line	45	9	3	3	3
最大仰角 Max. boom angle (°)	65	70	74	76	78
最小仰角 Min.boom angle (°)	26	50	60	64	71
2节臂 2nd section	0.0%	50.0%	100.0%	100.0%	100.0%
3节臂 3nd section	0.0%	0.0%	0.0%	26.7%	56.7%
4节臂 4nd section	0.0%	0.0%	0.0%	26.7%	56.7%
5节臂 4nd section	0.0%	0.0%	0.0%	26.7%	56.7%

起重性能表Load charts



起重性能表 Load charts



11.32–32.86m



2km/h



吊臂在正前方 boom over front



9t

R/L	11.32	15.30	19.28	25.67	32.86
3.0	21.1				
3.5	18.9	17.7			
4.0	17.0	16.0	15.1		
5.0	14.0	13.1	12.5	12.4	
6.0	11.6	10.9	10.4	10.5	10.3
7.0	9.8	9.2	8.7	9.0	8.9
8.0	7.7	7.4	7.2	7.8	7.8
9.0		5.4	5.2	6.6	6.8
10.0		4.0	3.8	5.1	5.9
12.0				3.0	3.8
14.0					2.3
倍率 Parts of line	4	4	4	3	3
最大仰角 Max. boom angle (°)	65	70	74	76	78
最小仰角 Min.boom angle (°)	26	32	44	53	59
2节臂 2nd section	0.0%	50.0%	100.0%	100.0%	100.0%
3节臂 3rd section	0.0%	0.0%	0.0%	26.7%	56.7%
4节臂 4nd section	0.0%	0.0%	0.0%	26.7%	56.7%
5节臂 4nd section	0.0%	0.0%	0.0%	26.7%	56.7%



起重性能表Load charts

起重性能表 Load charts



11.32–32.86m



2km/h



吊臂在正前方 boom over front



5.5t

R/L	11.32	15.30	19.28	25.67	32.86
3.0	20.3				
3.5	18.1	17.0			
4.0	16.3	15.3	14.5		
5.0	13.4	12.6	11.9	11.9	
6.0	11.1	10.4	9.9	10.0	9.9
7.0	7.9	7.6	7.3	8.6	8.5
8.0	5.6	5.3	5.0	6.4	7.4
9.0		3.6	3.4	4.8	5.6
10.0				3.5	4.3
12.0					2.5
倍率 Parts of line	4	4	4	3	3
最大仰角 Max. boom angle (°)	65	70	74	76	78
最小仰角 Min. boom angle (°)	26	32	53	59	63
2节臂 2nd section	0.0%	50.0%	100.0%	100.0%	100.0%
3节臂 3rd section	0.0%	0.0%	0.0%	26.7%	56.7%
4节臂 4nd section	0.0%	0.0%	0.0%	26.7%	56.7%
5节臂 4nd section	0.0%	0.0%	0.0%	26.7%	56.7%



11.32–32.86m



2km/h



吊臂在正前方 boom over front



0t

R/L	11.32	15.30	19.28	25.67	32.86
3.0	19.0	17.8			
3.5	16.9	15.9	15.0		
4.0	15.2	14.3	13.5		
5.0	10.6	10.1	9.8	11.1	10.7
6.0		6.0	5.8	7.4	8.5
7.0				4.8	5.8
8.0				3.1	4.0
9.0					2.8
倍率 Parts of line	4	4	4	3	3
最大仰角 Max. boom angle (°)	65	70	74	76	78
最小仰角 Min. boom angle (°)	26	45	60	64	71
2节臂 2nd section	0.0%	50.0%	100.0%	100.0%	100.0%
3节臂 3nd section	0.0%	0.0%	0.0%	26.7%	56.7%
4节臂 4nd section	0.0%	0.0%	0.0%	26.7%	56.7%
5节臂 4nd section	0.0%	0.0%	0.0%	26.7%	56.7%

起重性能表Load charts



起重性能表 Load charts



43.2m



9.5m-17.5m



7.2m



360°



9t

工作幅度 Working radius	9.5m副臂 9.5m of jib						17.5m副臂 17.5m of jib					
	副臂安装角 Jib offset angle											
	0°		20°		40°		0°		20°		40°	
	起重量 Lifting load	起升 高度 Lifting height	起重量 Lifting load	起升 高度 Lifting height	起重量 Lifting load	起升 高度 Lifting height	起重量 Lifting load	起升 高度 Lifting height	起重量 Lifting load	起升 高度 Lifting height	起重量 Lifting load	起升 高度 Lifting height
12	5	50.4										
14	4.7	49.7	3.6	49.4			2.4	58.1				
16	4.4	49	3.4	48.7	2.9	47.4	2.3	57.5				
18	4.1	48.2	3.3	47.8	2.8	46.6	2.2	56.7	1.7	56.1		
20	3.9	47.2	3.1	46.9	2.6	45.6	2.1	56	1.7	55.3		
22	3.7	46.2	3	45.8	2.6	44.5	2	55.1	1.6	54.4	1.3	52.2
24	3.3	45.1	2.9	44.7	2.6	43.3	1.9	54.1	1.6	53.4	1.2	51.1
26	2.7	43.8	2.8	43.4	2.4	42	1.8	53.1	1.5	52.4	1.2	50
28	2.2	42.4	2.5	42	2.4	40.6	1.7	51.9	1.5	51.2	1.1	48.8
30	1.8	40.9	2	40.5	2.2	38.9	1.7	50.7	1.4	49.9	1.1	47.5
32	1.4	39.2	1.6	38.8	1.8	37.2	1.6	49.3	1.3	48.6	1	46
34	1.1	37.4	1.3	36.9	1.4	35.2	1.4	47.9	1.3	47.1	1	44.4
36			1	34.8	1.1	33	1.1	46.3	1.2	45.4	1	42.7
38							0.9	44.5	1.1	43.6	0.9	40.8
40									1	41.7	0.9	38.7





起重性能表Load charts

起重性能表 Load charts



43.2m



9.5m–17.5m



7.2m



360°



5.5t

工作幅度 Working radius	9.5m副臂 9.5m of jib						17.5m副臂 17.5m of jib					
	副臂安装角 Jib offset angle											
	0°		15°		30°		0°		15°		30°	
	起重量 Lifting load	起升 高度 Lifting height	起重量 Lifting load	起升 高度 Lifting height	起重量 Lifting load	起升 高度 Lifting height	起重量 Lifting load	起升 高度 Lifting height	起重量 Lifting load	起升 高度 Lifting height	起重量 Lifting load	起升 高度 Lifting height
12.0	5	50.4										
14.0	4.7	49.7	3.6	49.4			2.4	58.1				
16.0	4.4	49	3.4	48.7	2.9	47.4	2.3	57.5	1.7			
18.0	4.1	48.2	3.3	47.8	2.8	46.6	2.2	56.7	1.7	56.1		
20.0	3.9	47.2	3.1	46.9	2.6	45.6	2.1	56	1.6	55.3		
22.0	3.2	46.2	3	45.8	2.6	44.5	2	55.1	1.6	54.4	1.3	52.2
24.0	2.5	45.1	2.9	44.7	2.6	43.3	1.9	54.1	1.5	53.4	1.2	51.1
26.0	2	43.8	2.3	43.4	2.4	42	1.8	53.1	1.5	52.4	1.2	50
28.0	1.6	42.4	1.8	42	2	40.6	1.7	51.9	1.4	51.2	1.1	48.8
30.0	1.2	40.9	1.4	40.5	1.6	38.9	1.5	50.7	1.3	49.9	1.1	47.5
32.0	0.9	39.2	1.1	38.8	1.2	37.2	1.2	49.3	1.3	48.6	1	46
34.0			0.8	36.9	0.9	35.2	0.9	47.9	1	47.1	1	44.4
36.0										45.4	1	42.7

起重性能表Load charts



起重性能表 Load charts

 43.2m

 9.5m-17.5m

 7.2m

 360°

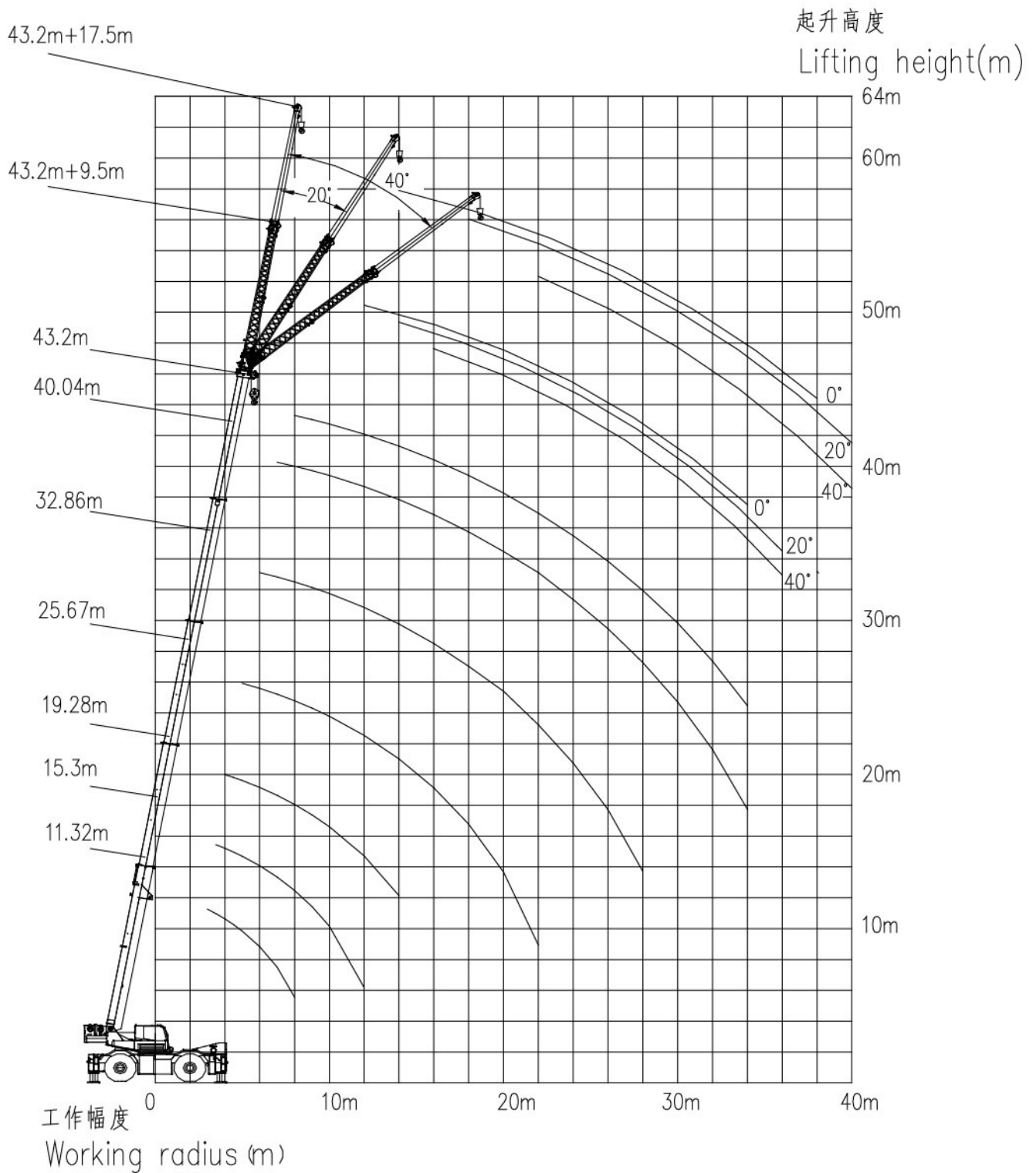
 0t

工作幅度 Working radius	9.5m副臂 9.5m of jib						17.5m副臂 17.5m of jib					
	副臂安装角 Jib offset angle											
	0°		20°		40°		0°		20°		40°	
	起重量 Lifting load	起升 高度 Lifting height	起重量 Lifting load	起升 高度 Lifting height	起重量 Lifting load	起升 高度 Lifting height	起重量 Lifting load	起升 高度 Lifting height	起重量 Lifting load	起升 高度 Lifting height	起重量 Lifting load	起升 高度 Lifting height
12.0	5	50.4										
14.0	4.7	49.7	3.6	49.4			2.4	58.1				
16.0	4.3	49	3.4	48.7	2.9	47.4	2.3	57.5				
18.0	3.3	48.2	3.3	47.8	2.8	46.6	2.2	56.7	1.7	56.1		
20.0	2.5	47.2	2.9	46.9	2.6	45.6	2.1	56	1.7	55.3		
22.0	1.8	46.2	2.2	45.8	2.5	44.5	2	55.1	1.6	54.4	1.3	52.2
24.0	1.3	45.1	1.6	44.7	1.9	43.3	1.7	54.1	1.6	53.4	1.2	51.1
26.0	0.9	43.8	1.2	43.4	1.4	42	1.2	53.1	1.5	52.4	1.2	50
28.0			0.8	42	1	40.6	0.9	51.9	1.4	51.2	1.1	48.8
30.0									1.1	49.9	1.1	47.5
32.0											1	46



作业范围图 Working range diagram

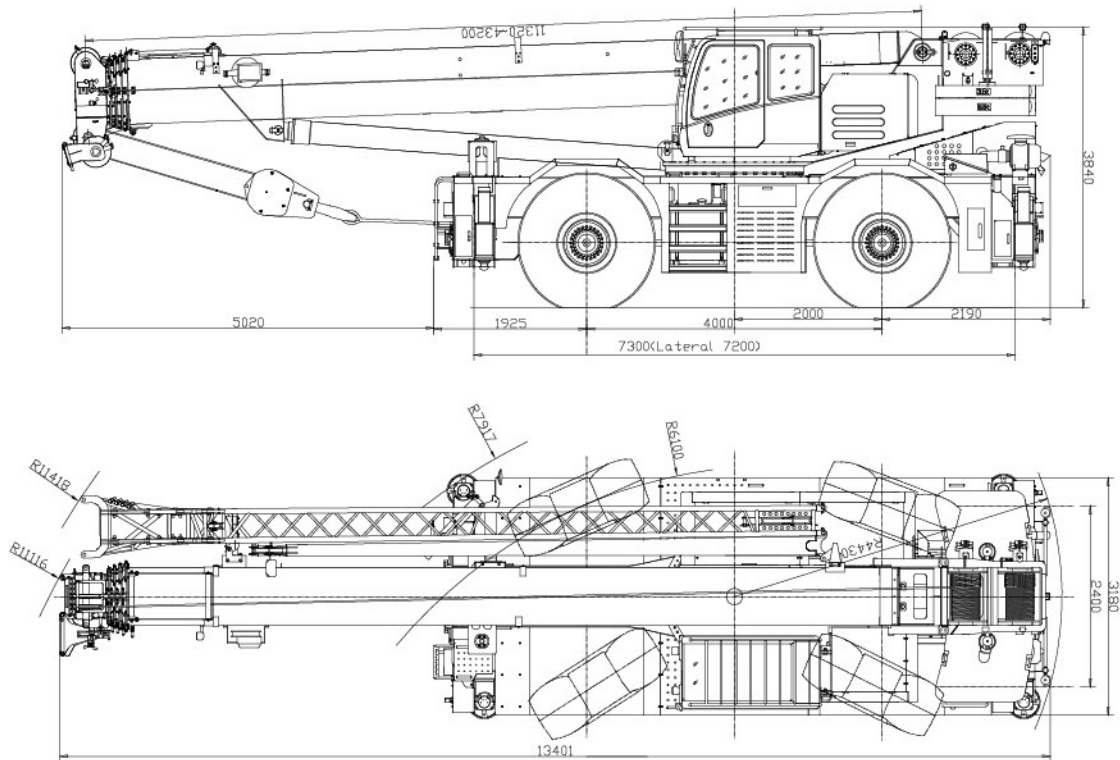
作业范围图 Working range diagram



技术规格（遵从技术改进）
Specifications(Subject to technology improvement)



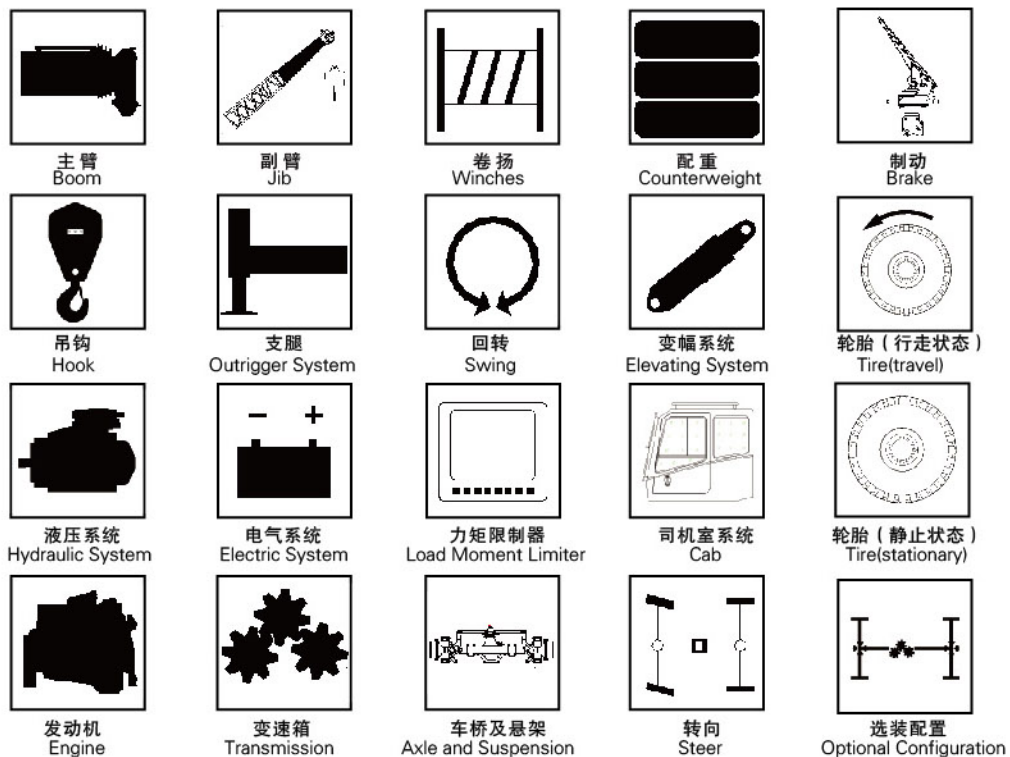
外形尺寸图（遵从技术改进） Dimensions(Subject to technology improvement)



注：尺寸单位为mm，整机为四轮转向行驶状态。

Note: Reference dimensions in mm. Dimensions of crane in travel configuration with four-wheel steering.

标识 Symbols



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